



# Discrete optimization: A quantum revolution?

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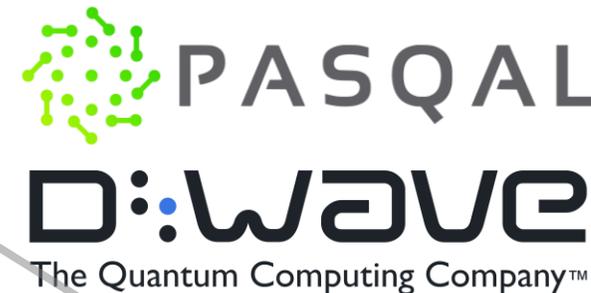
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# Quantum Computing



**Qiskit**



Universal quantum computer

Quantum annealing

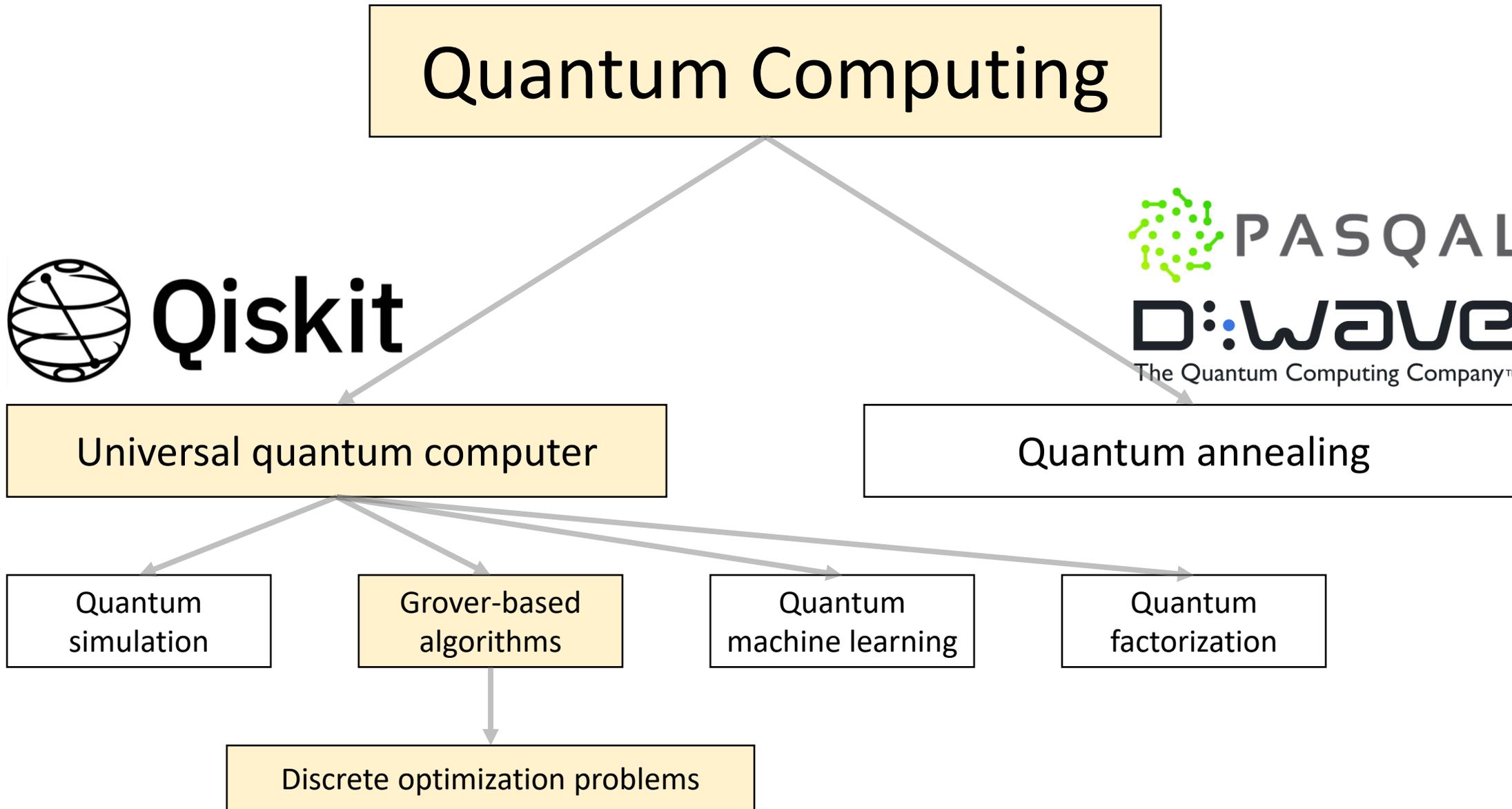
Quantum simulation

Grover-based algorithms

Quantum machine learning

Quantum factorization

Discrete optimization problems



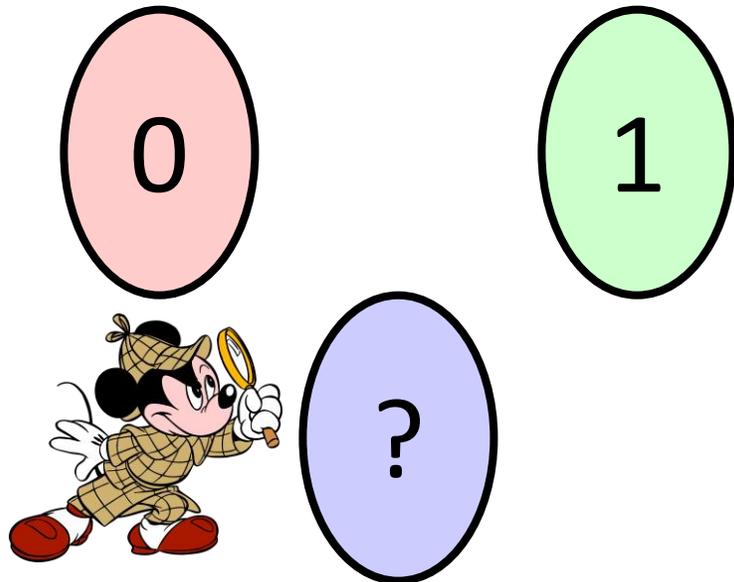
# Discrete optimization problems

- In the most general form:
  - optimize  $g(x_1, x_2, \dots, x_n)$
  - subject to
  - $x_i \in \Omega_i, \forall i: 0 \leq i \leq n$
  - (any other constraint)
- Where:
  - $g(x)$  is the objective function that evaluates assignment  $x = \{x_1, x_2, \dots, x_n\}$ .
  - $n$  is the number of decision variables.
  - $x_i$  is the  $i^{\text{th}}$  decision variable.
  - $\Omega_i$  is the set of discrete values that can be assigned to decision variable  $x_i$ .
- Objective function and/or constraints **do not have to be linear!**
- Examples include: 3SAT, knapsack, TSP, complex non-linear integer programming problems, and most other OR problems discussed here at INFORMS

# Basic unit of information: Classic vs quantum

## Classical computing

- Bit.
- Can take on values **0** and **1**.



## Quantum computing

- Qubit.
- Can take on values **0** and **1**.
- Can be in a **superposition** state.
- Only after observing the qubit, the state collapses to basis state **0** or **1**.
- The probability that the state of a qubit collapses to **0** or **1** depends on the **superposition**.
- In case of a uniform **superposition**, there is a 50% chance to collapse into either **0** or **1**.

# Solving the binary knapsack problem

- $n = 3$  items.
- Maximum weight  $W = 4$ .
- Optimal solution value  $V^* = 5$ .
- Solution  $\mathbf{x} = \{x_1, x_2, \dots, x_n\}$ .
- Weight of  $\mathbf{x}$  is  $W_x$ .
- Value of  $\mathbf{x}$  is  $V_x$ .
- Function  $f(\mathbf{x})$  evaluates whether solution  $\mathbf{x}$  is valid; has weight  $W_x$  that does not exceed weight capacity  $W$ , and value  $V_x$  is at least equal to  $V^*$ .

$i$	$w_i$	$v_i$
1	2	3
2	3	1
3	2	2
$n = 3$	$W = 4$	$V^* = 5$
$\mathbf{x} = \{x_1, x_2, x_3\}$	$W_x = \sum w_i x_i$	$V_x = \sum v_i x_i$
$f(\mathbf{x}) = 1$ if $W_x \leq W$ and $V_x \geq V^*$		

# Solving the binary knapsack problem

- Classical computing:
  - Full enumeration requires  $2^n = 8$  calls to function  $f(x)$ .
  - Each call to  $f(x)$  requires  $\eta$  operations.
  - In case of knapsack,  $\eta = O(n) \rightarrow$  full enumeration has complexity  $O(n2^n)$ .
  - Best classical algorithm to solve binary knapsack has complexity  $O(n\sqrt{2^n})$ .
- Quantum computing:
  - Given a (uniform) superposition of three qubits, only a single call to  $f(x)$  is required to obtain  $f(x)$  for each possible solution  $\rightarrow$  complexity  $O(n)$ ?
  - Each solution, however, has probability  $2^{-n} = 0.125$  to be measured  $\rightarrow$  we only have a 12.5% chance to measure 101.

$i$	$w_i$	$v_i$
1	2	3
2	3	1
3	2	2
$n = 3$	$W = 4$	$V^* = 5$
$x = \{x_1, x_2, x_3\}$	$W_x = \sum w_i x_i$	$V_x = \sum v_i x_i$
$f(x) = 1$ if $W_x \leq W$ and $V_x \geq V^*$		

$x$	$W_x$	$V_x$	$f(x)$	$P(x)$
000	0	0		0.125
100	2	3		0.125
010	3	1		0.125
110	5	4		0.125
001	2	2		0.125
101	4	5	1	0.125
011	5	3	0	0.125
111	7	6	0	0.125



# Grover's algorithm

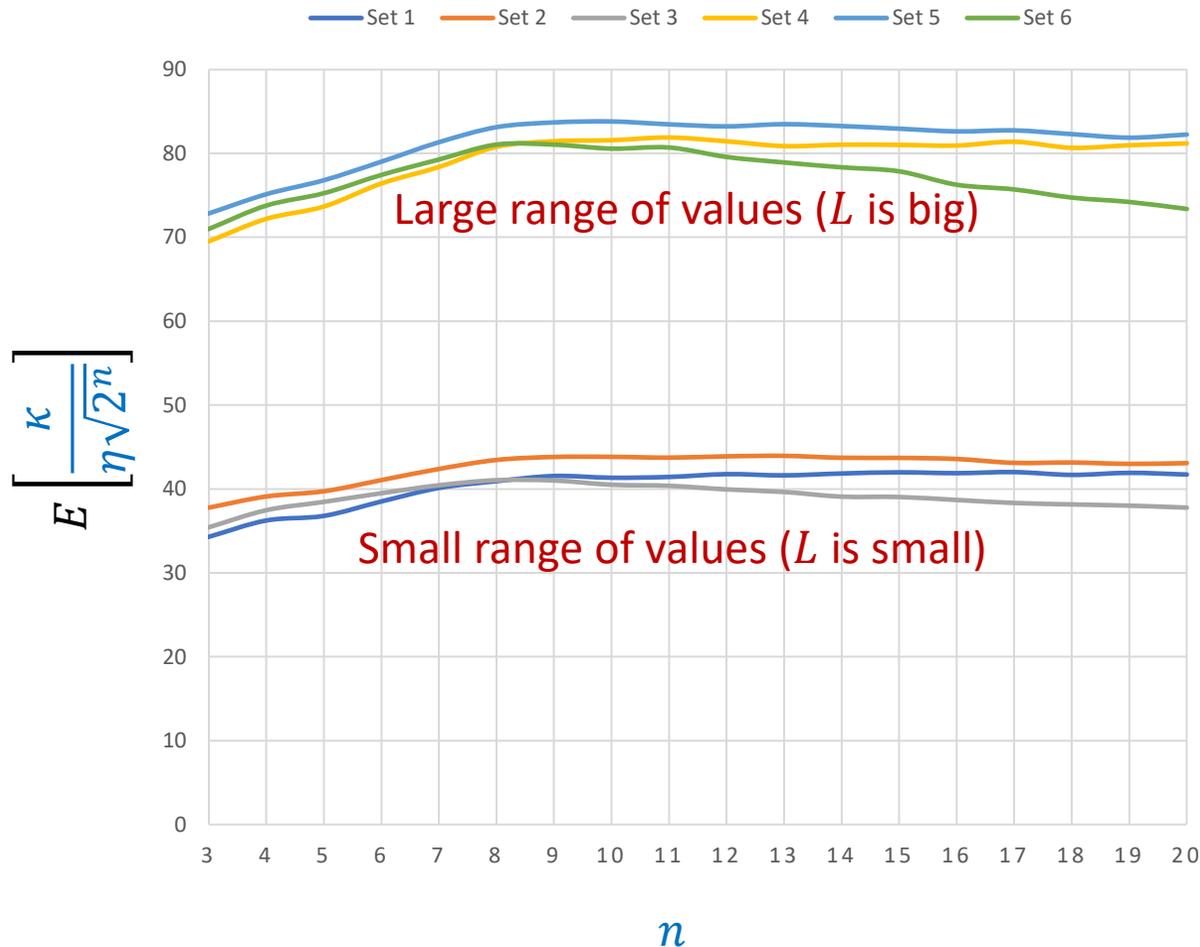


- Grover's algorithm maximizes the probability to measure a solution  $x$  that has  $f(x) = 1$  using roughly  $\sqrt{2^n/m}$  iterations, where  $m$  is the number of solutions for which  $f(x) = 1$ .
- In our example, there is only one solution (i.e., 101) that has  $f(x) = 1$ ; that has  $V \geq V^*$  (i.e.,  $m = 1$ ).
- If  $m = 1$ , to find 101, Grover's algorithm needs roughly  $\sqrt{2^n}$  iterations (and hence calls to  $f(x)$ ).
- To find 101 on a classical computer, we need up to  $2^n$  calls to  $f(x)$  if we use full enumeration → Grover's algorithm achieves a quadratic speedup?
- When using Grover's algorithm to solve discrete optimization problems, we face two problems:
  - We don't know  $m$ .
  - We don't know  $V^*$ .

# Binary Search Procedure (BSP)

- To solve these problems, we propose a Binary Search Procedure (BSP).
- First, to find the optimal value  $V^*$ , BSP initializes a minimum value  $V_{min}$  and a maximum value  $V_{max}$ . Next, binary search is used to evaluate different values of  $V$  until  $V^*$  is identified.
- For each value  $V$ , BSP also evaluates different values of  $m$ :
  - If, for a given value of  $m$ , a valid solution  $x$  is measured (that has value  $V_x \geq V$ ), we let  $V_{min} = V + 1$ .
  - If no valid solution can be found, we let  $V_{max} = V - 1$ .
- Million-dollar question: do we still achieve a **quadratic speedup**?

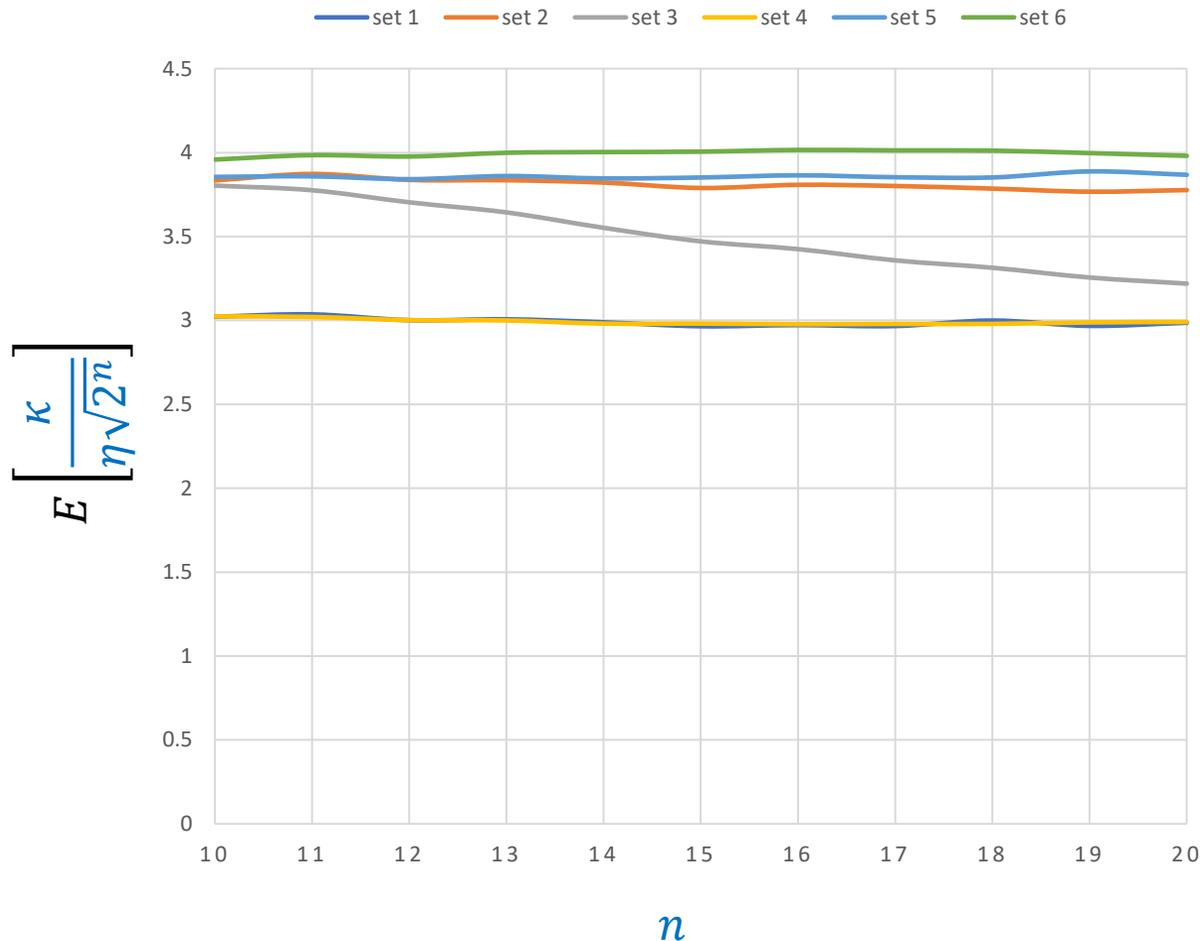
# BSP: Results and complexity



- We use **BSP** to solve 1000 knapsack problems for:
  - Values of  $n \in [3, \dots, 20]$ .
  - 6 problem sets
- We report the expected number of operations required to solve a knapsack problem ( $\kappa$ ) divided by  $\eta\sqrt{2^n}$ .
- Complexity **BSP** is  $O(\eta L\sqrt{2^n})$ , where  $L$  is a logarithmic term depending on the range of values of knapsack items.
- No **quadratic speedup** due to logarithmic term  $L$ , however: can we do better?

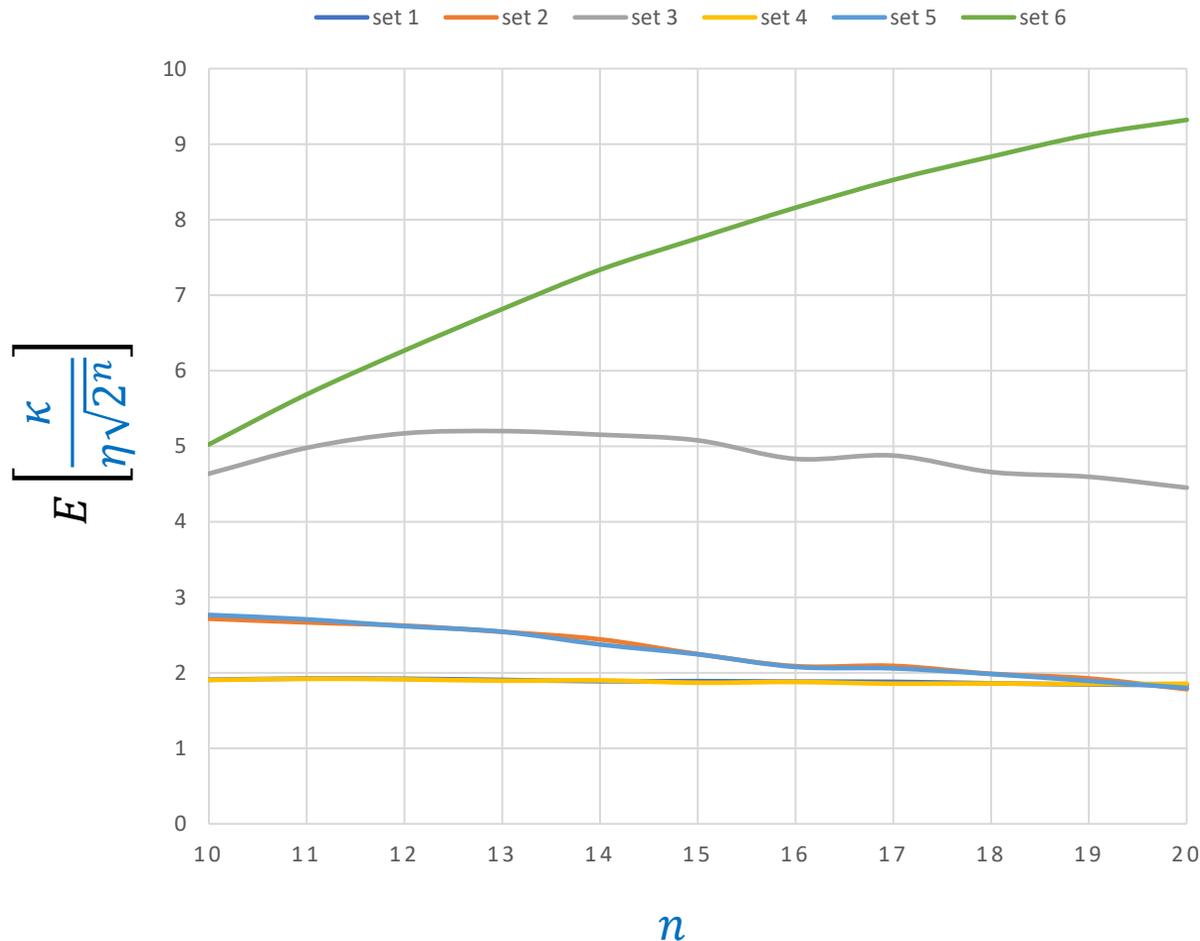


# Random Ascent Procedure (RAP)



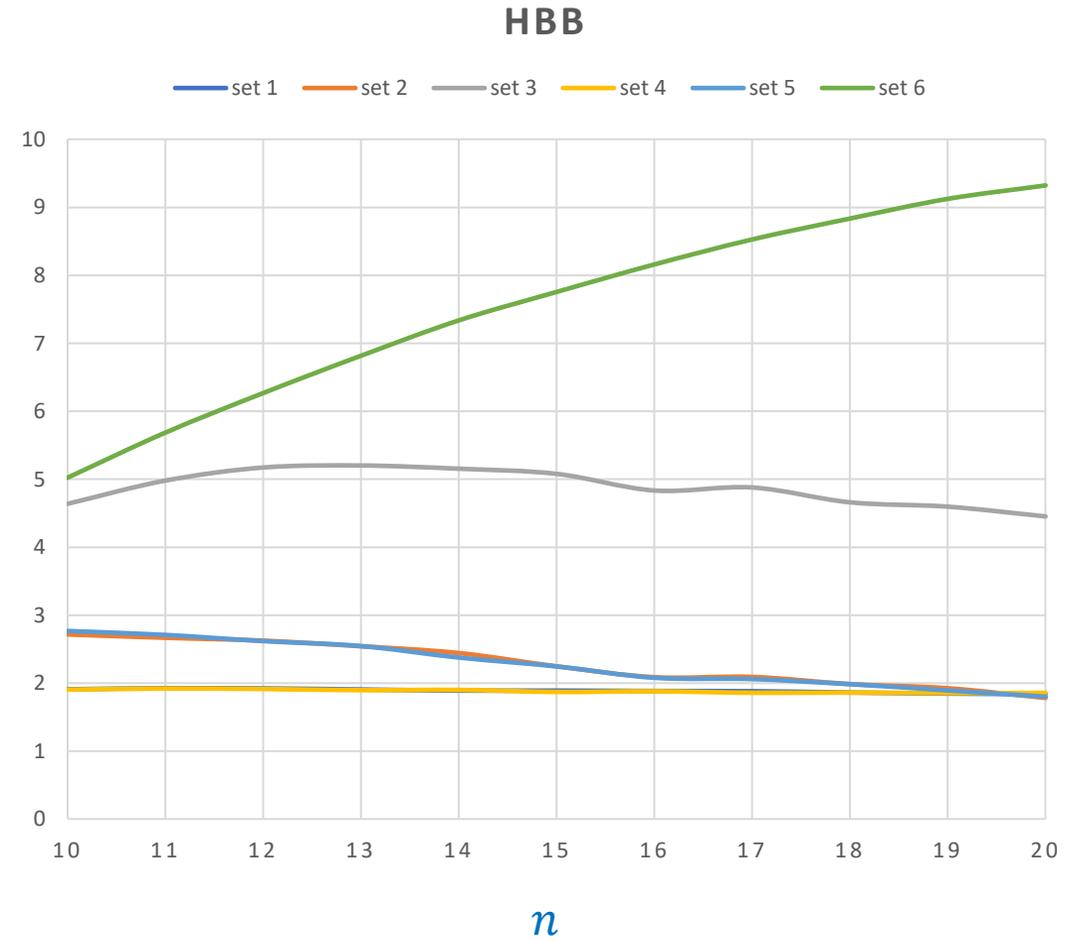
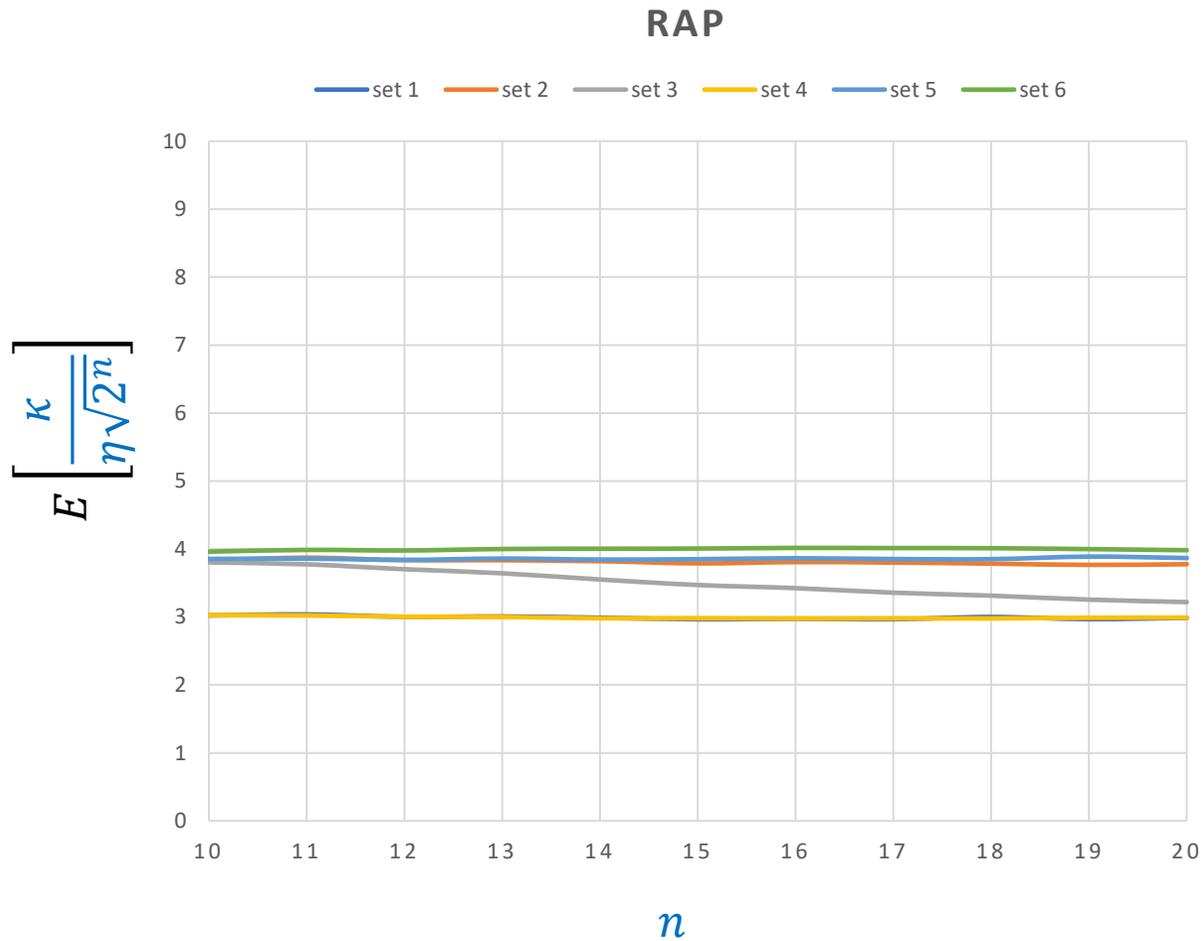
- Iterative procedure that uses Grover's algorithm to find a solution that has a better value than the best-found solution.
- If we measure, a better solution is chosen at random from the set of solutions that can still improve the best-found solution.
- RAP has worst-case expected complexity  $O(\eta \sqrt{2^n})$ .
- recall that for knapsack the best classical algorithm also has complexity  $O(\eta \sqrt{2^n})$ .

# Hybrid Branch-and-Bound (HBB)

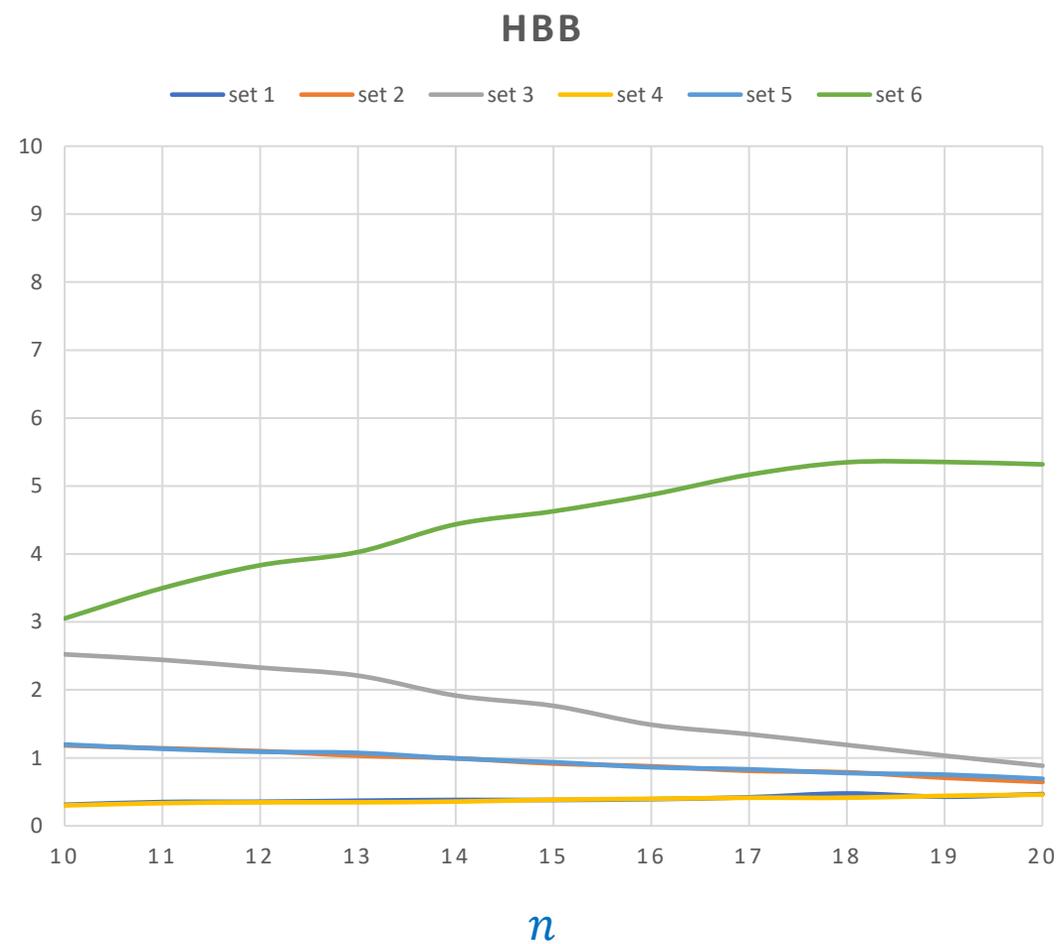
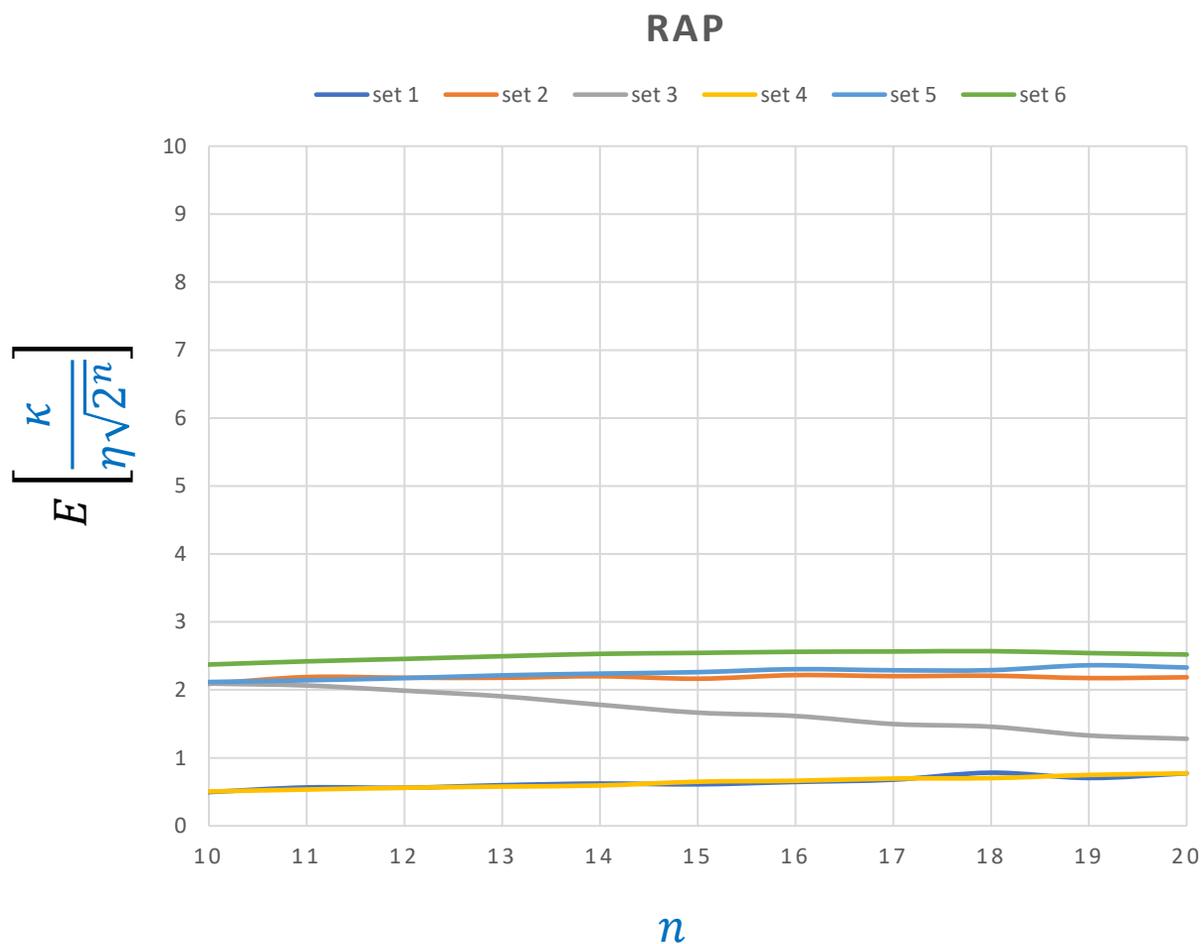


- Uses a tree that has  $n$  levels.
- At each level  $i$ , you create a node for each discrete value that can be assigned to decision variable  $x_i$  (i.e., you create a partial solution where the first  $i$  decision variables have been assigned a value).
- In each node, we use Grover's algorithm to see if we can find a solution for the remaining  $n - i$  decision variables that improves the best-found solution:
  - If such a solution can be found, we branch.
  - If no solution can be found, we fathom the node.
- HBB also has complexity  $O(\eta \sqrt{2^n})$ .

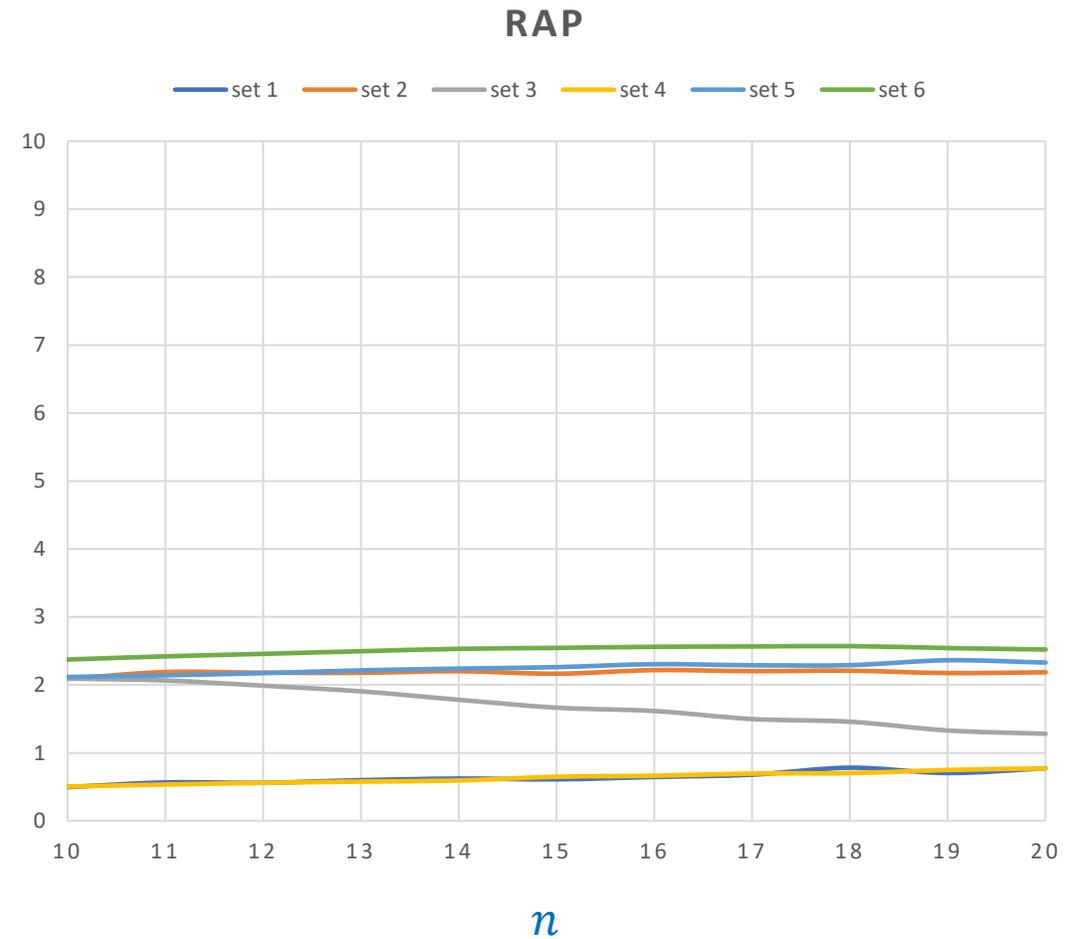
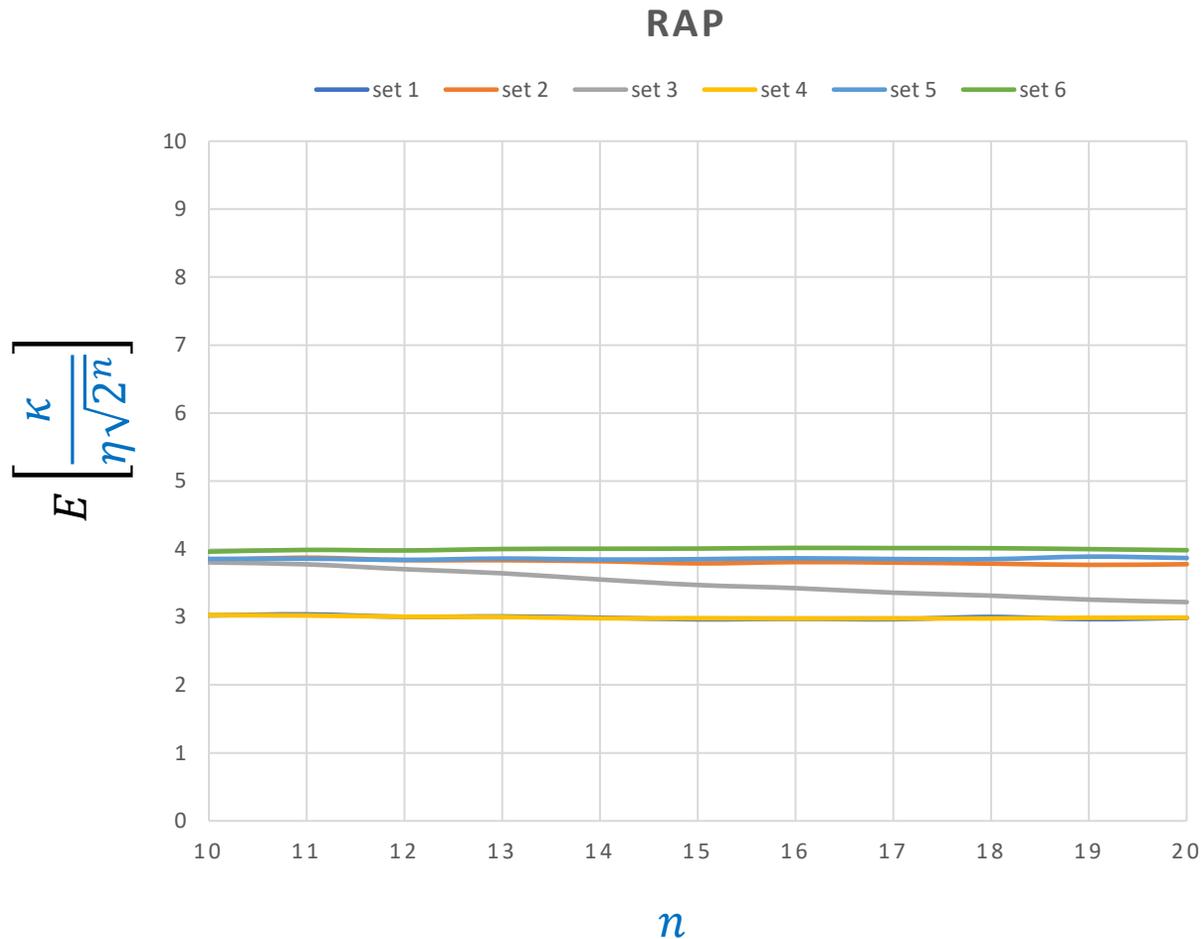
# RAP versus HBB (solving to optimality)



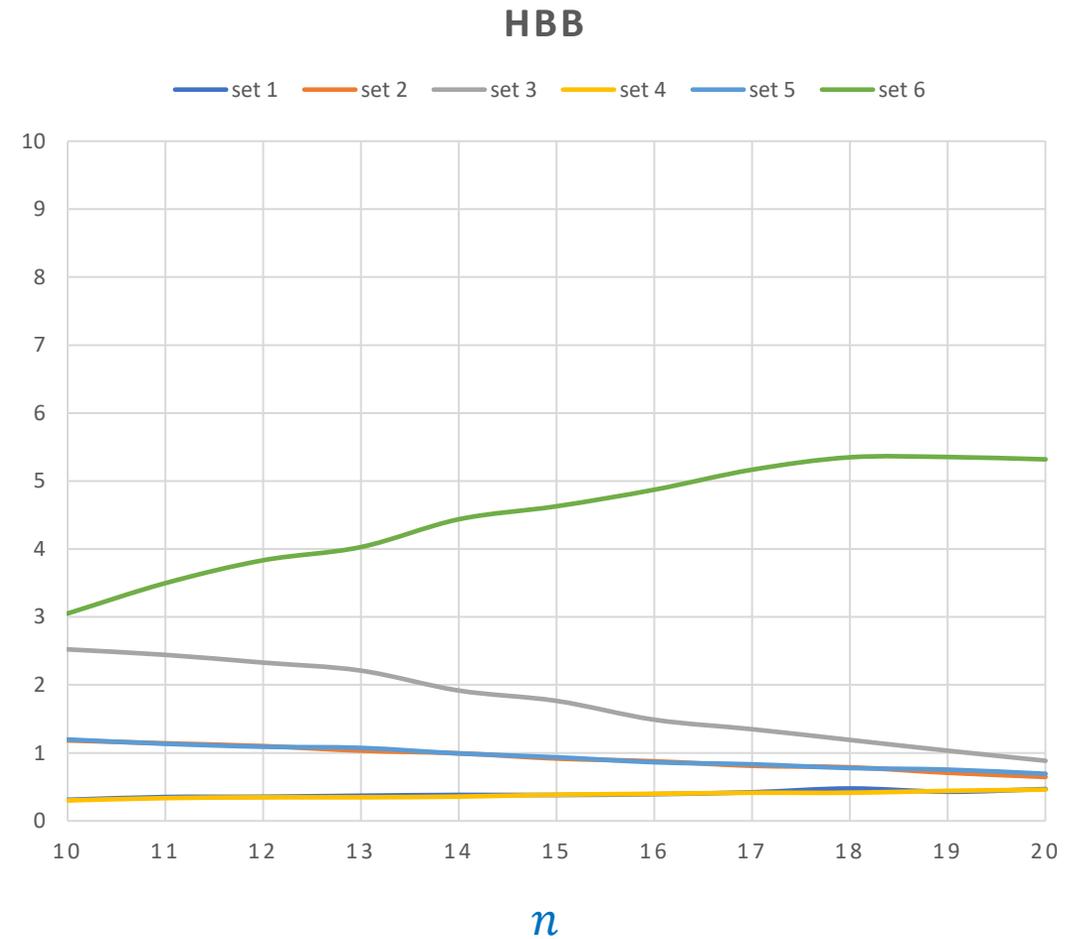
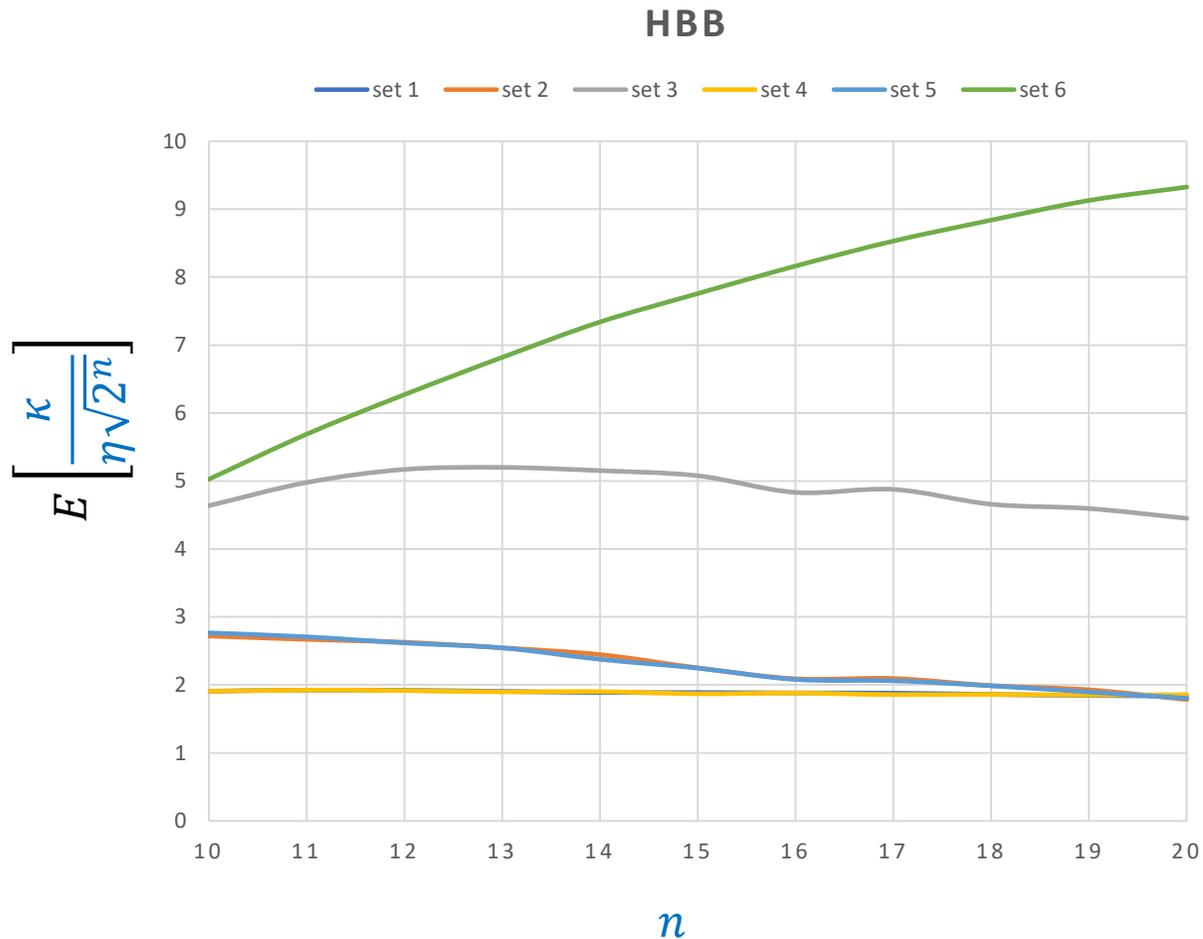
# RAP vs HBB (finding optimal solution for 1<sup>st</sup> time)



# RAP: Time to find optimal solution versus time to find optimal solution for 1<sup>st</sup> time



# HBB: Time to find optimal solution versus time to find optimal solution for 1<sup>st</sup> time



# Conclusions

- We identified the problems faced when using Grover's algorithm to solve discrete optimization problems.
- We use Grover's algorithm as a subroutine in:
  - BSP (Binary Search Procedure).
  - RAP (Random Ascent Procedure).
  - HBB (Hybrid Branch-and-Bound).
- We use these algorithms to solve 108000 binary knapsack problems.
- We show that:
  - RAP & HBB require at most  $O(\eta\sqrt{2^n})$  operations to find the optimal solution.
  - RAP & HBB match performance of best classical algorithms when solving knapsack.
  - RAP & HBB can also be used as heuristics using far less operations.
  - RAP & HBB can be used to solve ANY discrete optimization problem to optimality.



4 responses submitted

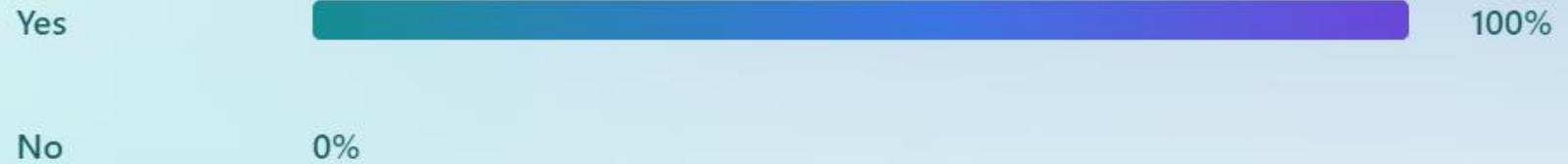
## Will quantum computing cause a revolution in the field of discrete optimization?

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# Want to know more?

- Read our three papers (currently under review):
  - Discrete optimization: A quantum revolution (Part I).
  - Discrete optimization: A quantum revolution (Part II).
  - Discrete optimization: Limitations of existing quantum algorithms.
- Available on SSRN and on my personal website ([www.cromso.com](http://www.cromso.com)).
- Coming soon to arXiv.
- Contact us:
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